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# Random spread and Forest Fires

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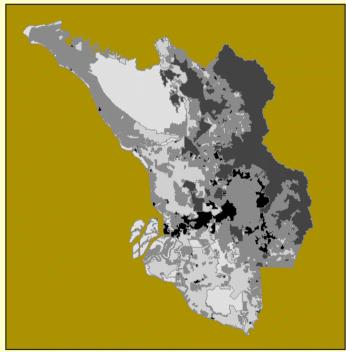
- Usual maps symbolize objects that *do exist* in the physical word,
- e.g. the Malaysian peninsula is *prior* to any geographer, and independent of him.

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### **Risks maps**

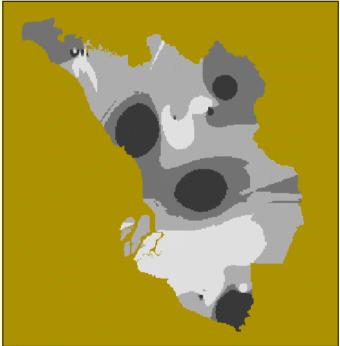
#### Consider now the two maps of forest fires parameters

#### *Fuel amount* : **θ**



*Relative Scale* : the lighter, the more fuel

#### Fire spread : p



Scale : 0 meter/mn (black) to 3 meters/mn (light)

#### Selangor State, Malaysia

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# A missing link

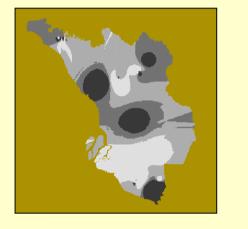
- When we draw the map of a risk, e.g. a spread fire, we describe a *scientific assumption*.
- There is *no actual object* in the physical word that the map symbolizes: it represents potentialities only.
- If we want to go from potentialities to the actual events, an *additional element* turns out to be necessary.

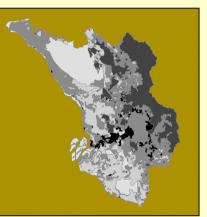
.....But how to handle it ?

## The missing link

*Fire spread* : **p** 

*Fuel amount* : θ





Red Co

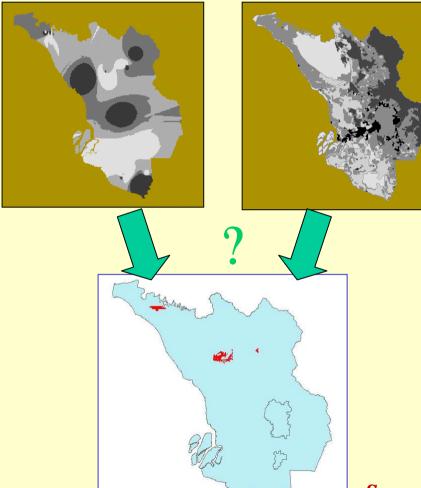
- How to go from these two maps to the burnt regions?
- Can we derive from them the duration of a fire ?
- and the size distribution of the burnt regions ?
- Without a model, surely not !

Scars from 2000 to 2004

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## A Pde?

- Classically, each Pde summarizes a conflict of elementary variations,
- but here, we are facing a space-time process whose all parameters act in the sense of the space invasion.

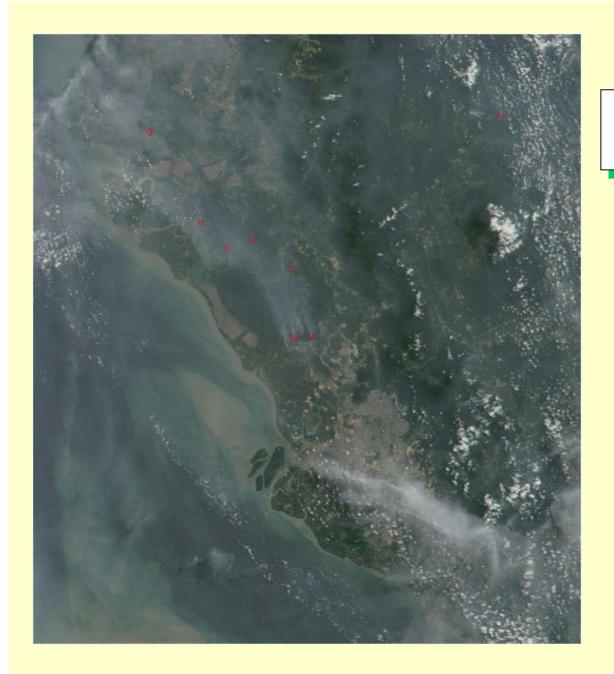
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How to introduce an element that balance the invasion?

the *hot spots* provide a third piece of information.

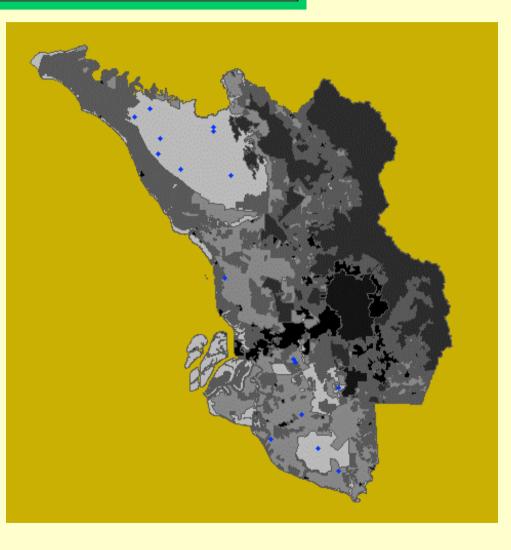


## **Hot Spots**

In red, the hot spots detected in Selangor, on August 12, 2005

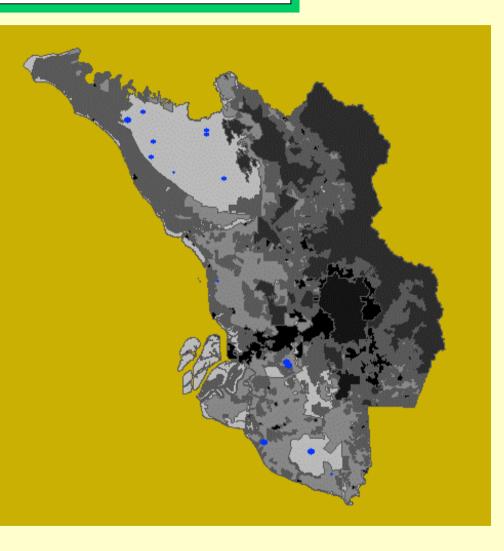
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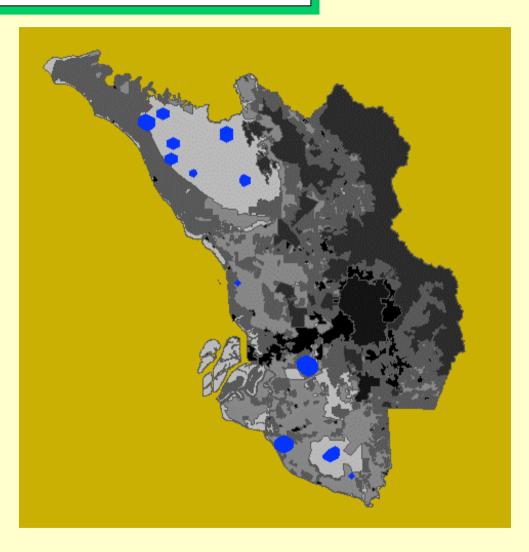
#### Initial hot spots



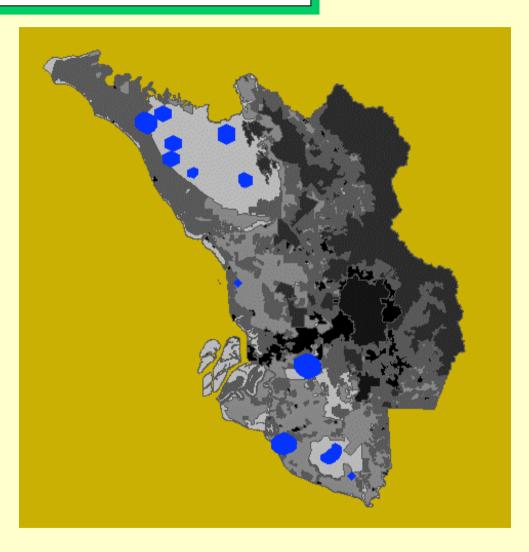
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The speed of expansion is given by the spread rate map

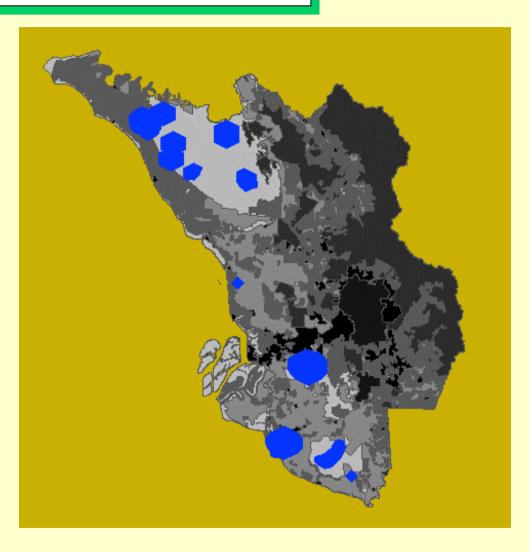




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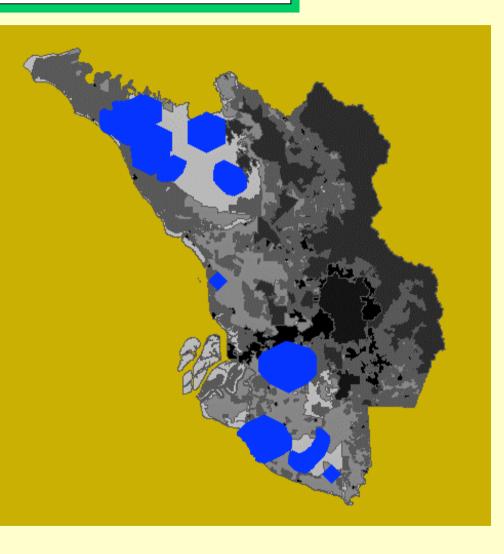


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When the seats expand according to the spread map, then they progressively *invade the whole space* 



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- It results in *predictions* for the
  - $\Rightarrow$  daily evolution of the fire;
  - $\Rightarrow$  the possible natural extinction,
  - $\Rightarrow$  location of the scar regions.
- Finally, it also leads to *simulations* of the fire propagation.

## **Random Closed Sets (or RACS)**

Let  $\mathbb{R}^d$  be the Euclidean space of dimension d,

 $\mathcal{F} = \mathcal{F}(\mathbb{R}^d)$  denotes the family of all closed sets of  $\mathbb{R}^d$ ,  $\mathcal{K} = \mathcal{K}(\mathbb{R}^d)$  the family of all compact sets.

- $\sigma$ -algebra : Given an element  $K \in \mathcal{K}$ , consider the class  $\mathcal{F}(K)$  of all closed sets that miss the compact set K. As K spans the family  $\mathcal{K}$ , the classes { $\mathcal{F}(K)$ ,  $K \in \mathcal{K}$ , } generate a  $\sigma$ -algebra.
- **RACS** : Moreover, as  $\mathcal{F}$  is a compact space, one can weight  $\sigma$  by probabilities P. Then each triplet (F, $\sigma$ ,P) *defines a RACS*.

This abstract definition of a RACS goes back to G.Matheron and D.G.Kendall. However, these authors made their approach more tractable by proving the following result.

## **The Matheron-Kendall theorem**

• *Characteristic Theorem* : Every RACS X is characterized by the datum of the probabilities

 $Q(K) = Pr \{ K \subseteq X^c \} \qquad K \in \mathcal{K}.$ 

Conversely, a family  $\{Q(K), K \subseteq \mathcal{K}\}$  defines a unique RACS if and only if 1- Q(K) is a **Choquet capacity** such that

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• **Choquet' capacity** : numerical function Q on  $\mathcal{K}$ , such that

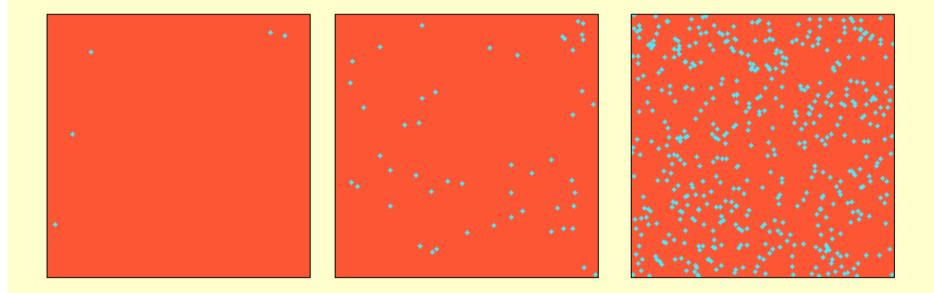
1-  $S_1(K; K_1) = Q(K) - Q(K \cup K_1)$  $S_n(K; K_1..K_n) = S_{n-1}(K; K_1..K_{n-1}) - S_n(K \cup K_n; K_1..K_{n-1})$ 

2-  $K_n \downarrow K$  implies  $Q(K_n) \uparrow Q(K)$ 

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## **Poisson points**

• Here are usual simulations of Poisson points (slightly dilated by a rhomb for the display)



#### They are «*usual*» in that the intensity $\theta(x)$ is *constant*

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A basic random set is that of the Poisson points, defined as follows

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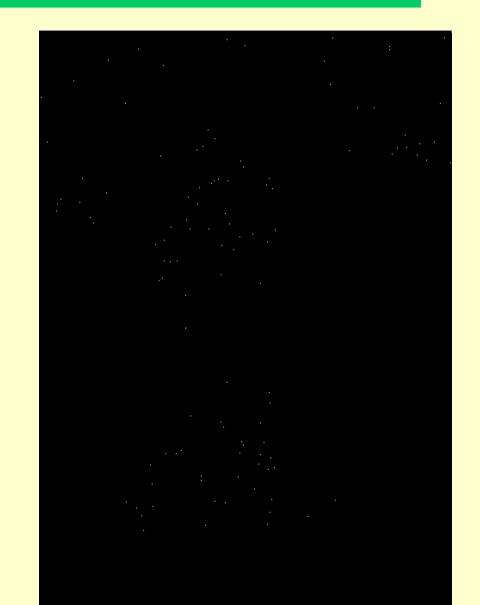
1 pointin dxis $\theta(dx)$ 0 pointin dxis $1 - \theta(dx)$ 

The functional Q(K) of Poisson points  $\theta$  is  $Q(K) = \exp\{-\int_{K} \theta(dx)\} = \exp\{-\theta(K)\}$ 

In some cases the intensity of the Poisson points can also *vary* through the space ...

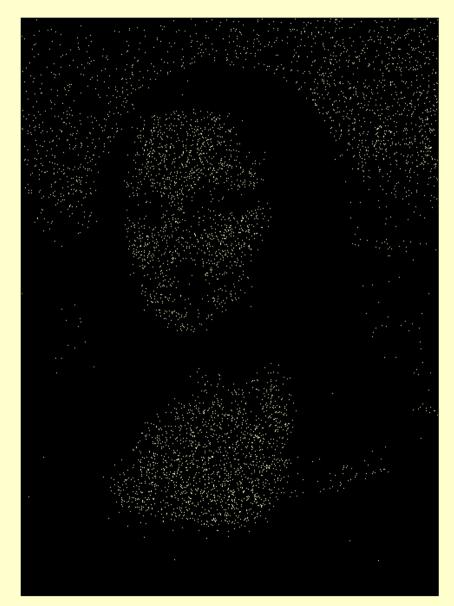
We still have the probability  $\theta(x) dx$ of one point in dx,

but  $\theta$  is now an underlying function of the space



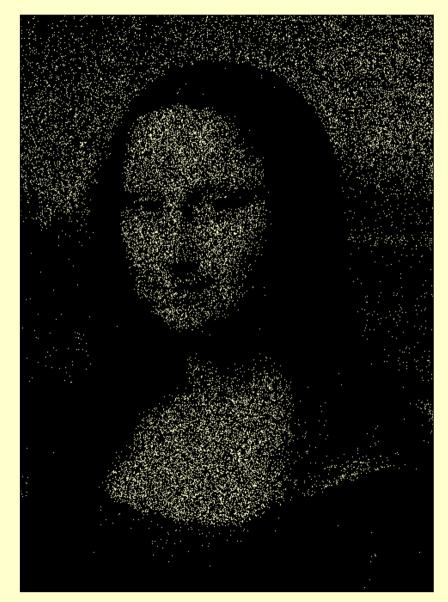
As  $\theta$  is multiplied by a constant factor,

the number of points increases



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#### And more again...

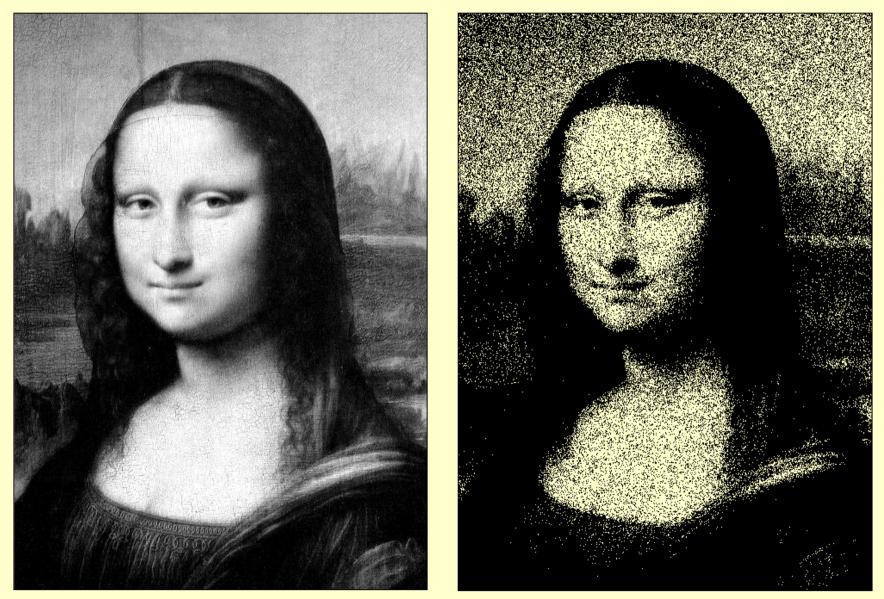


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#### And more and more ...



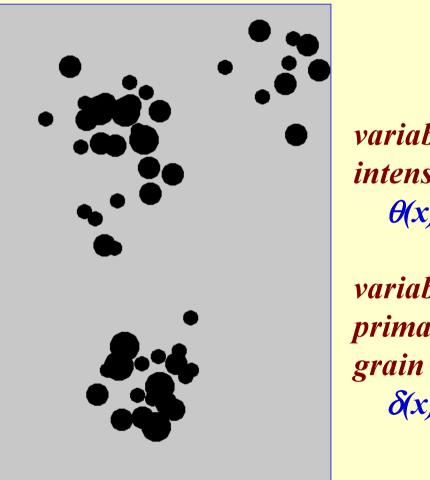
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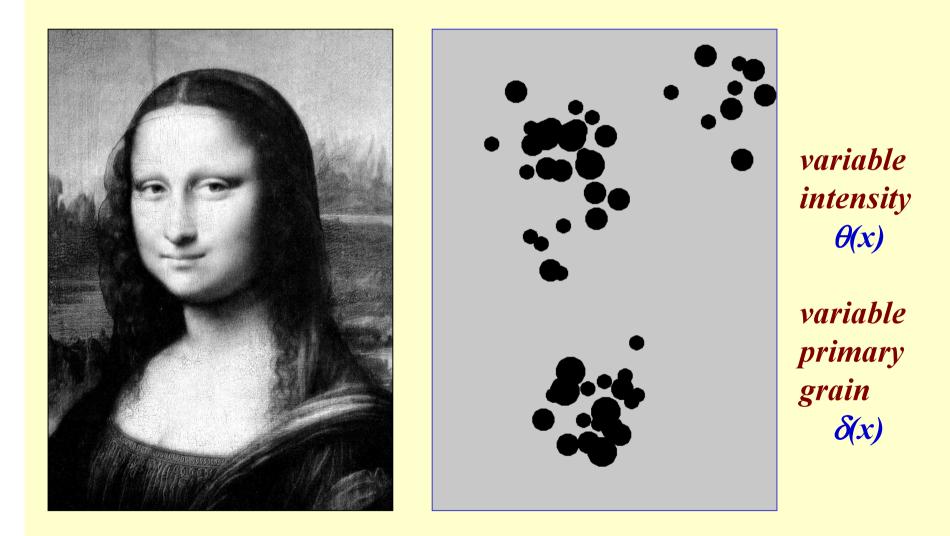
## **Boolean random set**



variable intensity  $\theta(x)$ variable primary

 $\delta(x)$ 

### **Boolean random set**



## **Two parameters**

Just as a Boolean random set, a random spread depends on

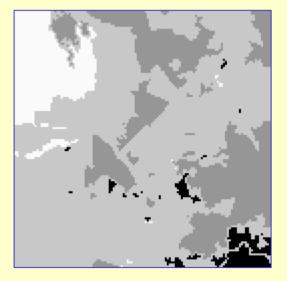
- The the intensity  $\theta$ , non negative numerical function
- The *dilation*  $\delta$ , *a set function*  $\mathbb{R}^d \to \mathcal{P}(\mathbb{R}^d)$

## **Two parameters**

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Here we take for set  $\delta(x)$  the disc of radius  $\rho$  at point x



**Point intensity**  $\theta$ 



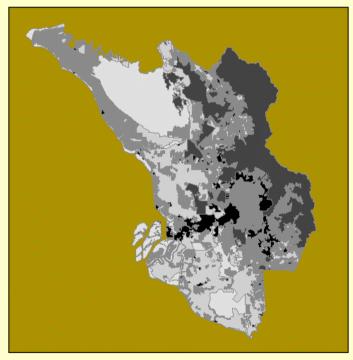
Dilation radius  $\rho$ 

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## **Parameters maps**

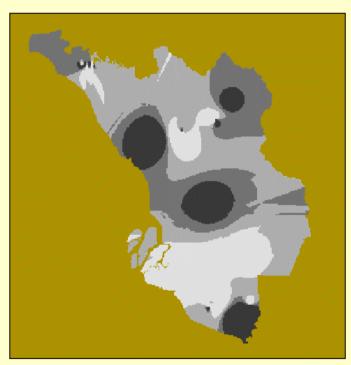
The two previous maps are details of the following risk maps

Fuel amount :  $\theta$ 



*Relative Scale* : the lighter, the more fuel

#### *Fire spread* : **p**



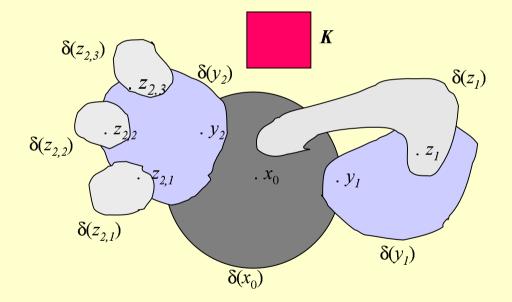
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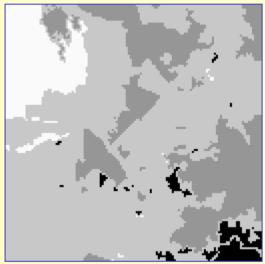
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#### The idea of a random spread is the following



## **Iterated spread**



**Point intensity** 



**Dilation radius** 

Fire  $X_n = \delta(I_{n-1}) = \delta \circ [\beta]^{n-1} (I_0)$ Seat  $I_n = \beta^n(I_0) = \bigcup \{ \delta(x_i) \cap J_i, x_i \in I_1 \}$ Examples of iterated Spread

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## **Functional of the Boolean set**

The Boolean Random set  $X(\theta, \delta)$  is characterized by the probabilities Q(K) that K misses the RACS, for all compact sets  $K \subset \mathbb{R}^d$  (Choquet characteristic). We have that  $Q(K) = \exp \{ - \int_{\zeta(K)} \theta(dx) \} = \exp \{ - \theta[\zeta(K)] \}$ 

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where  $\zeta$  is the *reciprocal* of  $\delta$ , i.e.  $\mathbf{x} \cap \zeta(\mathbf{K}) \neq \phi \quad \Leftrightarrow \quad \delta(\mathbf{x}) \cap \mathbf{K} \neq \phi$ 

# **Functional of iterated spread**

Let us calculate the functionals  $Q_1 \dots Q_n$  of spreads  $X_1 \dots X_n$ .

• The first step is just Boolean, so that the Choquet characteristic  $Q_1(K) = \exp \{ -\theta[\zeta(K) \cap \zeta(x)] \}$ 

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- Now, to say that K misses the n<sup>th</sup> fire starting from x is equivalent to saying that K misses the (n-1)<sup>th</sup> fire from y, cond. upon  $y \in \delta(x_0)$ . This results in the induction relation

$$Q_n(K) = \exp [1 - \int_{\zeta(x)} \theta(dy) Q_{n-1}(K | y)]$$

## **Reciprocal dilation**

• *Reciprocal dilation*: Again we meet the reciprocal dilation  $\zeta$  of  $\delta$  i.e. such that  $x \cap \zeta(K) \neq \phi \iff \delta(x) \cap K \neq \phi$ .

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- *Variable*  $\delta$  But in the application to forest fires,  $\delta$  varies from 1 to 5 from place to place. Which conditions must we demand to  $\delta$  to get a non trivial expression for  $\exp\left[-\int_{\zeta(K)} \theta(dz) g(z)\right]$ ?



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Dilation  $\delta$  is said to be *compact* when

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- 1- the structuring function  $x \to \delta(x)$  is u.s.c. from  $\mathbb{R}^d$  into  $\mathcal{K}$ ,
- 2- the union  $\bigcup \{ \delta_{-x}(x), x \in \mathbb{R}^d \}$  has a compact closure.

The second axiom implies that when x is far away enough, then  $\delta(x)$  surely misses K

# **Compact dilation**

- When  $\delta$  is compact, then
  - $\zeta$  also is compact,
  - $\delta$  and  $\zeta$  are u.s.c. mappings from  ${\mathcal F}$  to  ${\mathcal F}$  and from  ${\mathcal K}$  to  ${\mathcal K}$

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The following result shows that compact dilations model the *geographical maps*, with their discontinuites (fires that stop at a river, for example)

• Let  $\delta(x)$  be the disc of centre x and radius r(x). When  $x \rightarrow r(x)$  is u.s.c. and  $r(x) < r_{max} < \infty$ then both  $\delta$  and  $\zeta$  are compact.

# Scars

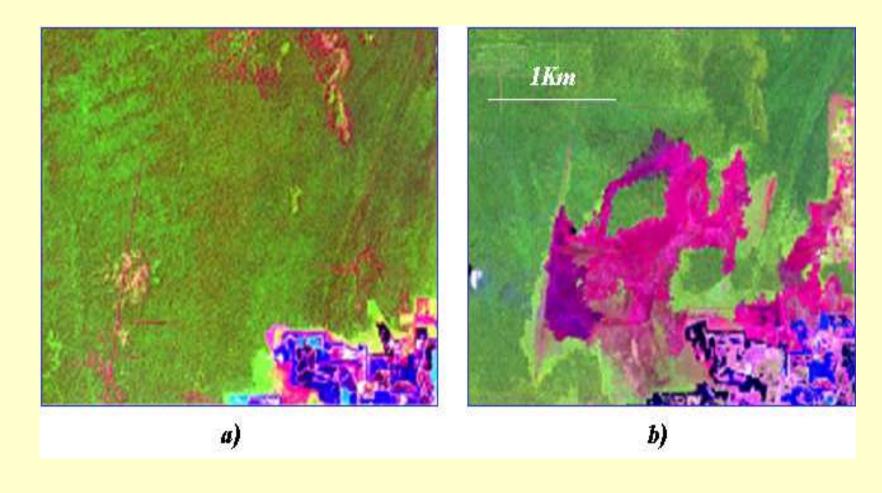
- Does the random spread model fit with actual fires data ?
- We can match the « *scars* » left by the fires union  $Y_n$  of all spreads  $X_i$  from steps 1 to n

 $\mathbf{Y}_{n} = \bigcup \left\{ \mathbf{X}_{n}, 1 \le i \le n \right\}$ 

But what happens after a long time, for Y∞?
Does the fire stop ? Does it expand indefinitely?



#### *Example of a scar* : A same region in 2000 and in 2004



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# **Upper bounds**

For finding an upper bound the scar  $\mathbf{Y}_{\mathbf{n}}$ , introduce the parameter

$$s(x) = \int_{\delta(x)} \theta(dx)$$

• When  $s(x) < s_{max} < 1$  then the scar  $Y_n$  is upper bounded by the Boolean RACS of primary grain  $\delta(x)$  and of intensity

 $\theta(\mathbf{x}) / 1 - \mathbf{s}_{\max}$ 

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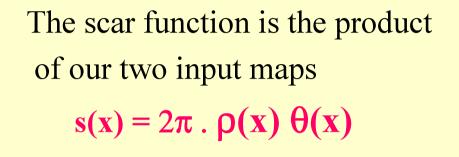
• When  $s(x) \le s_{max} < 1$  then the scar  $Y_n$  is upper bounded by the Boolean RACS of primary grain  $\delta(x)$  and of intensity

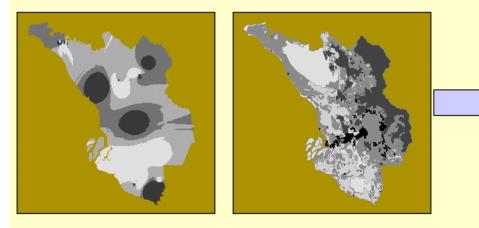
 $\theta(\mathbf{x}) / 1 - \mathbf{s}_{\max}$ 

• When not, the scar can expand indefinitely.

This suggests to compare the map of s(x) with the actual scares.

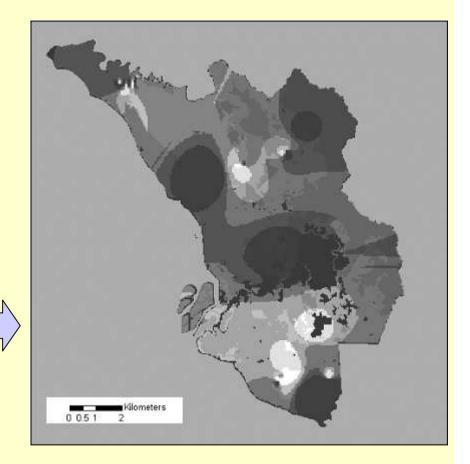
# **Scar function**







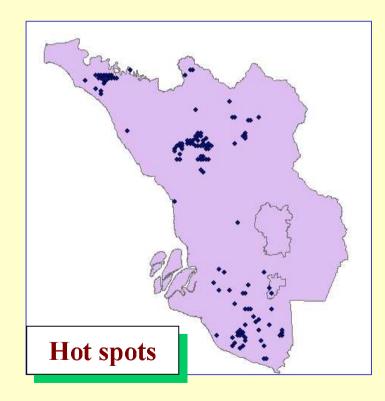
Fuel amount  $\theta/k$ 

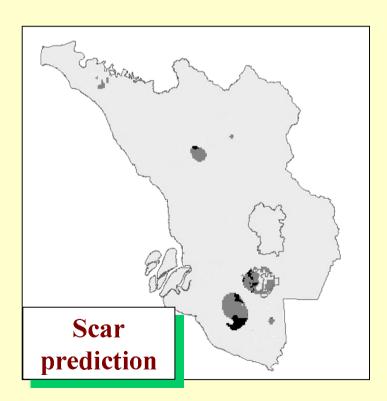


Scar function of Selangor

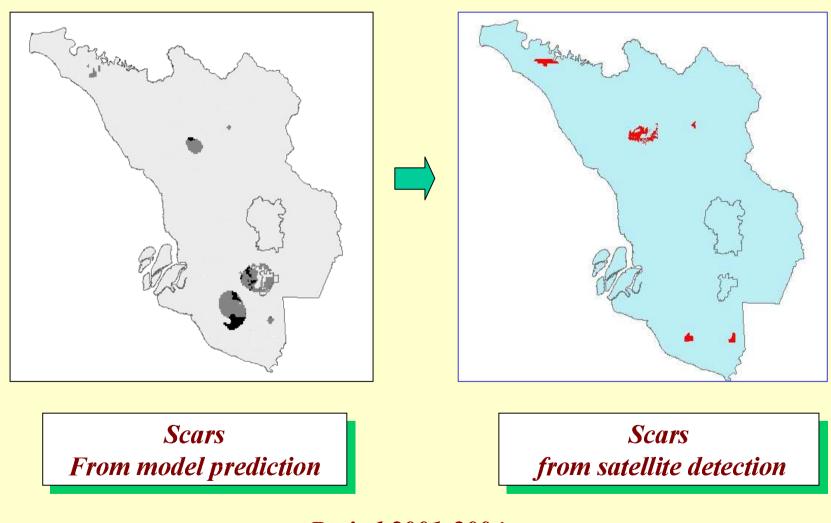
# Hot spots

- We obtain a predictor of the scars by *thresholding* the scar function **s** above k,
- The seasonal parameter k is estimated by the *hot spots number*





## Results



Period 2001-2004



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- For forest fires, it results in correct predictions of the *scars*.



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- This approach relies on the stochastic model of *Random Spread*, which generalizes *Boolean random set*.
- For forest fires, it results in correct predictions of the *scars*.
- The model is currently tested on the daily spreads.

Thank you very much

for your attention !

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